# Rohit Punjabi

Software Engineer

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#### **EDUCATION:**

**Master of Science in Computer Science** DigiPen Institute of Technology, Redmond, WA

**Bachelor of Engineering in Information Technology** 

Thadomal Shahani Engineering College, Mumbai, MH

#### SKILLS:

Programming Languages	:	C++, C#, Python, Lua
Libraries	:	OpenGL, SDL, FMOD, TensorFlow, NumPy
Tools	:	GitHub, Jira, Jupyter Notebook, Visual Studio
Game Engines	:	Unity3D, Unreal 4

### **PROJECTS:**

## **Programmer | 3D Custom Game Engine**

- Working in an Agile development environment to make a 3D game engine from scratch.
- Created an Audio System for the engine using FMOD Core API
- Integrated a robust game state manager into the game engine that uses a stack-based approach to enable seamless and responsive transitions between different stages.
- Developing game mechanics, systems, and features that align with the game's vision and target audience

### **Convolutional Neural Network**

- Developed a CNN to classify images for image processing, using Python, TensorFlow, NumPy.
- Pre-processed data using techniques such as normalization, and image resizing to optimize the model's performance. •
- Visualized the results using techniques such as accuracy curves, validation curves to gain insights into the model's performance.

### **Soft Body Simulation**

- Demonstrated soft body simulation of cube with 125 mass points. •
- Each mass point connected with a spring mass damping system.
- Applied Runge-Kutta 4<sup>th</sup> order numerical method for integration and Hooke's law for Spring system.

### AI Programmer | 2D Component Based Engine

- Developed a robust custom 2D game engine from scratch.
- Designed and implemented a custom behavior tree system for the boss enemy. •
- Implemented 2D Collision Detection algorithms such as AABB, and circle collision detection.
- Developed an Input Handling system using Lua Scripting to provide a flexible way to map inputs to in-game actions.

### A\* Pathfinding

- Implemented the A\* pathfinding algorithm in C++ to solve the problem of finding the shortest path between two points on a 2D grid.
- Utilized four admissible heuristics like Manhattan, Chebyshev, Octile, Euclidean and changeable weights.
- Applied Rubber banding and Smoothing (Catmull-Rom) on the path.

### **Planning with Smart Objects**

- Collaborated with 2 team members to design and implement a tech demo showcasing the use of Goal Oriented Action Planning with Smart Objects in Unreal engine.
- Developed a goal-driven approach for programming game characters that allowed for dynamic and adaptive gameplay experiences.

### **Shooting Madness | 3D mobile game**

- Implemented a system to save the player's score using Unity's PlayerPrefs class, to track and store the player's high scores across multiple sessions.
- Developed a touch joystick control system that enables smooth and intuitive camera movement in mobile games.

Expected May 2023

May 2021

September 2022 – Current

January 2023

November 2022 – December 2022

January 2022 – April 2022

March 2022 – April 2022

February 2022

May 2020

